

Behavioural Hybrid Process Calculus

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Hybrid Systems

Language

Continuous dynamics

- mechanical movement
- chemical reactions
- electrical circuits

Discrete dynamics

- collisions
- valves, pumps, switches
- digital control

Examples of Hybrid Systems

Embedded

- Phone
- TV
- Vehicle

Traffic Control Systems

- Highway Supervision
- Air Traffic Management
- Sea Traffic Management

Production Processes Control and Robotics

- Chemical industry
- Energy (power generation)
- Food industry

$$P := a.P \mid [\varphi].P \mid \bigoplus_{i \in I} P_i$$

$$\mid P \parallel_A^H P \mid P[\sigma] \mid B$$

$$\{B(v) \xrightarrow{\varphi} B'(v) \mid v \in I\},$$

$$\{B(w) \xrightarrow{\varphi} B'(w) \mid w \in J\}, I \neq \emptyset$$

$$\frac{\bigoplus_{v \in I \cup J} B(v) \xrightarrow{\varphi} \bigoplus_{v \in I} B'(v)}$$

Hybrid bisimulation is a congruence

Bisimilar processes can be substituted

Process Calculus Ingredients

Trajectories & their continuations

Synchronization only on specified actions & signals

Behavioural approach

- Trajectory-prefix
- Superposition
- Parallel Composition
- Separation of Concerns
- Continuous Behaviour

Choice is made when it is really time to do it

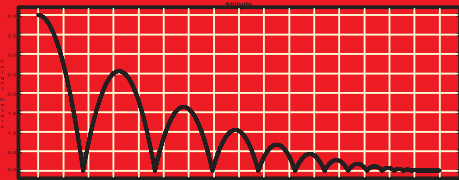
Discrete and continuous behaviours can be separated syntactically

Hybrid Transition System

$$HTS = \langle S, A, \rightarrow, W, \Phi, \rightarrow_c \rangle$$

- S is a state space,
- A is a set of (discrete) action names,
- $\rightarrow \subseteq S \times E \times S$ is a (discrete) transition relation ($s \xrightarrow{a} s'$),
- W is a signal space,
- Φ is a set of (initial) trajectories $\varphi : (0, t] \rightarrow W$ for $t \in \mathbb{R}^+$
- $\rightarrow_c \subseteq S \times \Phi \times S$ is a (continuous) transition relation ($s \xrightarrow{\varphi} c s'$)

Bouncing ball



$$B B (h_0, v_0) =_{df} [h, v : \Phi (h_0, v_0) \mid h = 0].$$

$$B B (0, -c v)$$

$$\Phi (h_0, v_0) = \left[\begin{array}{l} h, v : h(0) = h_0, v(0) = v_0 \\ \dot{h} = v, \dot{v} = -g \end{array} \right]$$

Plans

Development of analytical techniques for hybrid systems in the BHPC framework

Simulation of BHPC